

Student Name Eugene Rush Student ID *****Doctoral ☐ Degree in Mechanical Engineering

Thesis Title:

Neural Basis of Locomotion in Legged Robots

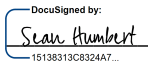
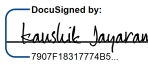
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Have you used live animals, animal tissue, or observational animal work which requires approval from the Institutional Animal Care and Use Committee (IACUC)? ☐ Yes ☒ No

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Attach the final copy of thesis/dissertation for committee review. While formatting changes may be requested by the Graduate School, the content of the attached document should be final.

**Approvals:**Committee Chair Name J. Sean HumbertSignature  Date Signed 4/15/2024Committee Member Name Kaushik JayaramSignature  Date Signed 4/15/2024

The final copy of this thesis has been examined by the signatories, and we find that both the content and the form meet acceptable presentation standards of scholarly work in the above-mentioned discipline.